

Range Minimum Queries and Lowest Common Ancestor

Inge Li Gørtz

Range Minimum Queries

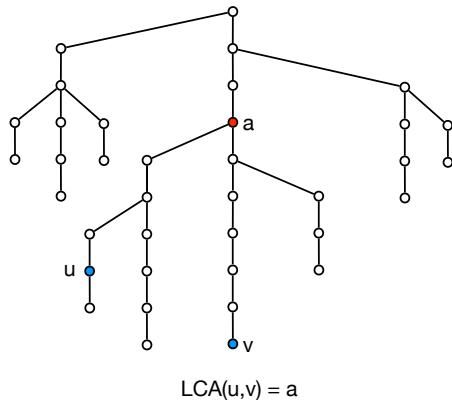
- **Range minimum query problem.** Preprocess array $A[0\dots n-1]$ of integers to support
 - $\text{RMQ}(i,j)$: return the (entry of) minimum element in $A[i\dots j]$.

0	1	2	3	4	5	6	7	8	9
1	7	12	8	2	5	1	4	8	3

- $\text{RMQ}(2,5) = 2$ (index 4)
- Basic (extreme) solutions
 - **Linear search:**
 - Space: $O(n)$. Only keep array (no extra space)
 - Time: $O(j-i) = O(n)$
 - **Save all possible answers:** Precompute and save all answers in a table.
 - Space: $O(n^2)$ pairs $\Rightarrow O(n^2)$ space
 - Time: $O(1)$

Lowest Common Ancestor

- **Lowest common ancestor problem.** Preprocess rooted tree T with n nodes to support
 - $\text{LCA}(u,v)$: return the lowest common ancestor of u and v .



Lowest Common Ancestor

- Basic (extreme) solutions
 - **Linear search:** Follow paths to root and mark when you visit a node.
 - Space: $O(n)$. Only keep tree (no extra space)
 - Time: $O(\text{depth of tree}) = O(n)$
 - **Save all possible answers:** Precompute and save all answers in a table.
 - Space: $O(n^2)$ pairs $\Rightarrow O(n^2)$ space
 - Time: $O(1)$

RMQ and LCA

- [Outline.](#)

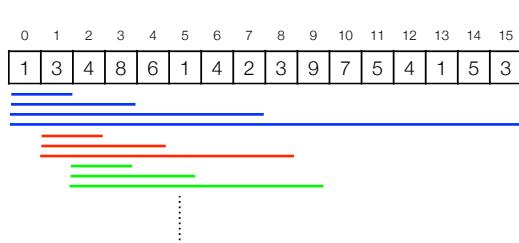
- Can solve both RMQ and LCA in linear space and constant time.
 - First solution to RMQ
 - Solution to a special case of RMQ called ± 1 RMQ.
 - See that RMQ and LCA are equivalent (can reduce one to the other both ways).
- Dynamic RMQ.

RMQ

Sparse table solution

RMQ: Sparse table solution

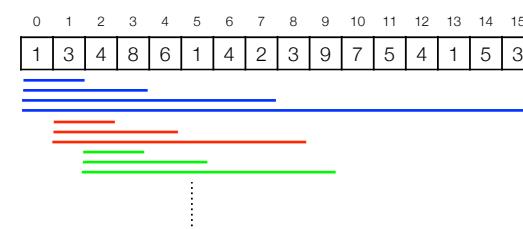
- Save the result for all intervals of length a power of 2.



0	1	2	3	4
1	3	4	8	6
1	3	3	3	1
2	4	4	1	1
3	8	6	1	1
4	6	1	1	1
5	1	1	1	1
6	4	2	2	1
7	2	4	2	1
8	3	3	3	1
9	9	7	4	
10	7	5	1	
11	5	1	1	
12	4	1	1	
13	1	1		
14	5	3		
15	3			

RMQ: Sparse table solution

- Save the result for all intervals of length a power of 2.



0	1	2	3	4
1	3	3	3	1
2	4	4	1	1
3	8	6	1	1
4	6	1	1	1
5	1	1	1	1
6	4	2	2	1
7	2	4	2	1
8	3	3	3	1
9	9	7	4	
10	7	5	1	
11	5	4	1	
12	4	1	1	
13	1	1		
14	5	3		
15	3			

- Space: $O(n \log n)$

RMQ: Sparse table solution

- Save the result for all intervals of length a power of 2.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	3	4	8	6	1	4	2	3	9	7	5	4	1	5	3

RMQ(6, 12) = ?

0	1	2	3	4
1	1	1	1	1
1	3	3	3	1
2	4	4	1	1
3	8	6	1	1
4	6	1	1	1
5	1	1	1	1
6	4	2	2	1
7	2	2	2	1
8	3	3	3	1
9	9	7	4	
10	7	5	1	
11	5	4	1	
12	4	1	1	
13	1	1	1	
14	5	3		
15	3			

- Space: $O(n \log n)$

RMQ: Sparse table solution

- Save the result for all intervals of length a power of 2.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	3	4	8	6	1	4	2	3	9	7	5	4	1	5	3

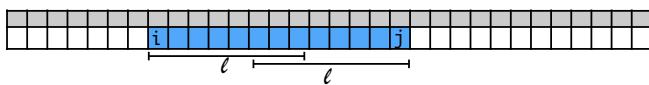
RMQ(6, 12) = min(RMQ(6,9), RMQ(9,12)) = min(2,4) = 2

0	1	2	3	4
1	1	1	1	1
1	3	3	3	1
2	4	4	1	1
3	8	6	1	1
4	6	1	1	1
5	1	1	1	1
6	4	2	2	1
7	2	2	2	1
8	3	3	3	1
9	9	7	4	
10	7	5	1	
11	5	4	1	
12	4	1	1	
13	1	1	1	
14	5	3		
15	3			

- Space: $O(n \log n)$

RMQ: Sparse table solution

- Query:



- Any interval is the union of two power of 2 intervals.
- k largest number such that $2^k \leq j - i + 1$.
- Lookup results for the two intervals and take minimum.
- Time: $O(1)$
- Space: $O(n \log n)$
- Preprocessing time: $O(n \log n)$
 - To compute results for length 2^i use results for length 2^{i-1} .

± 1 RMQ

RMQ: Linear space

- Consider ± 1 RMQ: consecutive entries differ by 1.

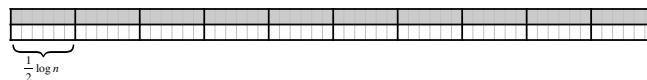
0	1	2	3	4	5	6	7	8	9	10	11	12
4	5	6	5	4	3	2	3	2	3	4	5	4

- 2-level solution: Combine

- $O(n \log n)$ space, $O(1)$ time
- $O(n^2)$ space, $O(1)$ time.
↓
- $O(n)$ space, $O(1)$ time.

± 1 RMQ

- Divide A into blocks of size $\frac{1}{2} \log n$



- 2-level data structure:

- Sparse table on blocks
- Tabulation inside blocks.

± 1 RMQ

- Divide A into blocks of size $\frac{1}{2} \log n$

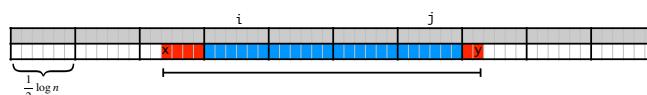


- 2-level data structure:

- Sparse table on blocks
- Tabulation inside blocks.

± 1 RMQ

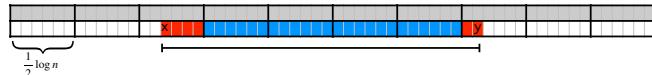
- Divide A into blocks of size $\frac{1}{2} \log n$



- 2-level data structure:

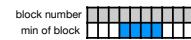
- Sparse table on blocks
- Tabulation inside blocks.

± 1 RMQ: Data structure on blocks



- Two new arrays.
 - Array A' : minimum from each block
 - B : position in A where $A'[i]$ occurs.
- Sparse table data structure on A' .
- Space: $O(|A'| \log |A'|) = O\left(\frac{n}{\log n} \cdot \log \frac{n}{\log n}\right) = O(n)$.
- Time: $O(1)$

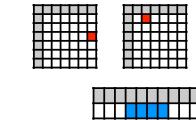
block number
min of block



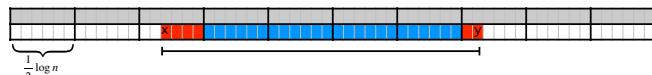
± 1 RMQ: Data structure inside blocks



- Precompute and save all answers for each block.
- Gives solution using
 - Space:



± 1 RMQ: Data structure inside blocks

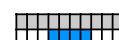
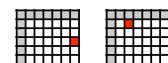


- Precompute and save all answers for each block.
- Gives solution using
 - Space: $O(n)$ + space for precomputed tables.
 - Time: $O(1) + O(1) + O(1) = O(1)$.

↑
2 table
lookups

↑
sparse
table

↑
 $\min\{\cdot, \cdot, \cdot\}$

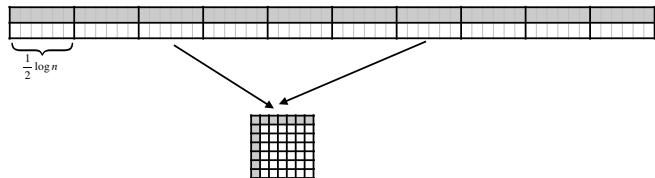


± 1 RMQ: Storing the tables

- Naively: $\log^2 n$ for each table => $n \log n$ space. 😞
- Observation:** If $X[i] = Y[i] + c$ then all RMQ answers are the same for X and Y .
 - $X = [7, 6, 5, 6, 5, 4]$
 - $Y = [3, 2, 1, 2, 1, 0]$
- Every block can be described by sequence of +1s and -1s:
 - $X = Y = -1, -1, +1, -1, -1$.
- How many different sequences are there?
 - length of sequence = $\frac{1}{2} \log n - 1$
 - #sequences = $2^{\frac{1}{2} \log n - 1} \leq \sqrt{n}$.

± 1 RMQ: Data structure inside blocks

- Precompute and save all answers for each sequence.
- Size of a table: $O(\log^2 n)$
- For each block save which precomputed table it uses.

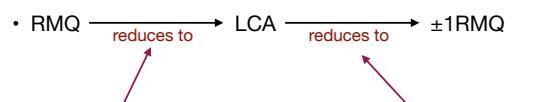


- Space: $O(\sqrt{n} \cdot \log^2 n) + O(n/\log n) = O(n)$
- Plugging into 2-level solution:
 - Space: $O(n) + \text{space for precomputed tables} = O(n)$.

LCA and RMQ

RMQ and LCA

- We will show



If there is a solution to LCA using $s(n)$ space and $t(n)$ time, then there is a solution to RMQ using $O(s(n))$ space and $O(t(n))$ time.

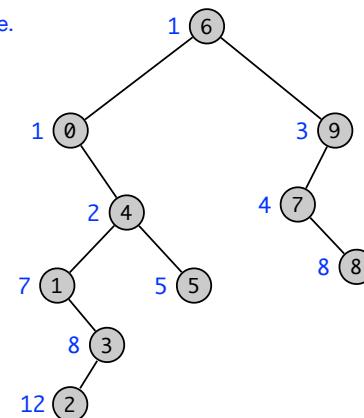
If there is a solution to ± 1 RMQ using $s(n)$ space and $t(n)$ time, then there is a solution to LCA using $O(s(n))$ space and $O(t(n))$ time.

RMQ to LCA

0	1	2	3	4	5	6	7	8	9
1	7	12	8	2	5	1	4	8	3

Below the table, four horizontal blue brackets indicate ranges: [0, 4], [5, 9], [1, 3], and [7, 8].

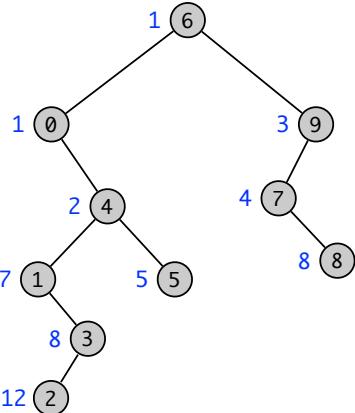
- Cartesian tree.



RMQ to LCA

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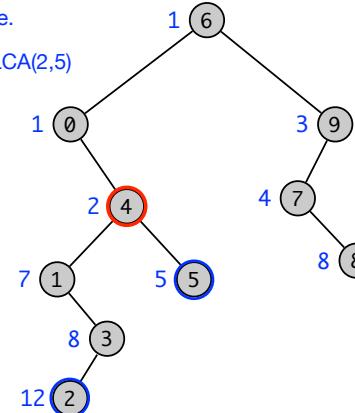
- Cartesian tree.
- $\text{RMQ}(2,5) = ?$



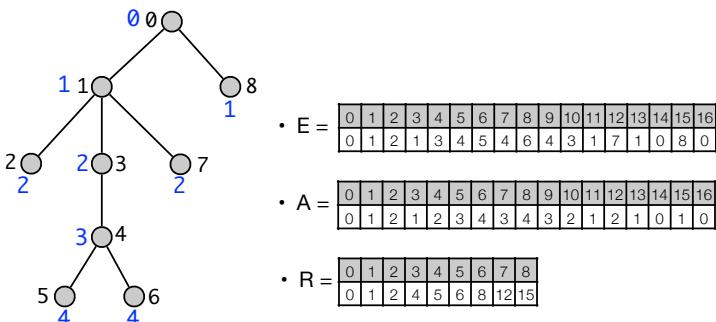
RMQ to LCA

0	1	2	3	4	5	6	7	8	9
1	7	12	8	2	5	1	4	8	3

- Cartesian tree.
- $\text{RMQ}(2,5) = \text{LCA}(2,5)$

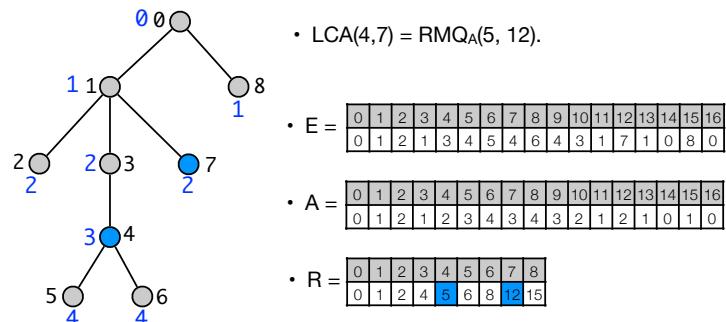


LCA to ± 1 RMQ



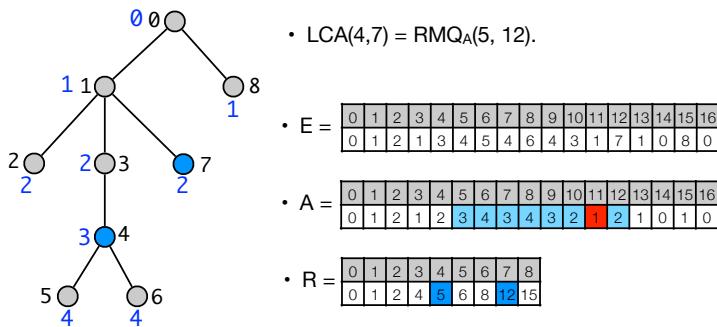
- E : Euler tour representation: preorder walk, write node preorder number of node when met.
- A : depth of node node in $E[i]$.
- R : first occurrence in E of node with preorder number i
- $\text{LCA}(i, j) = E[\text{RMQA}(R[i], R[j])]$.

LCA to ± 1 RMQ



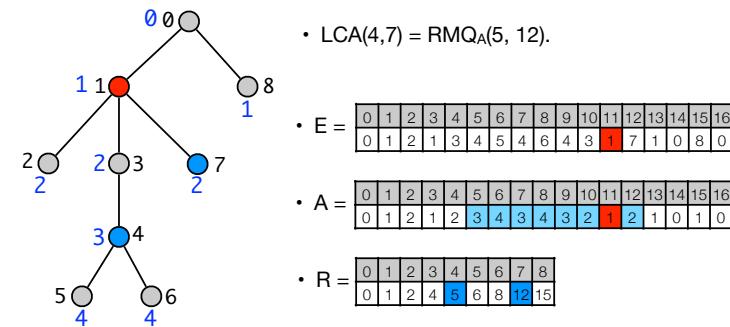
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LCA to ± 1 RMQ



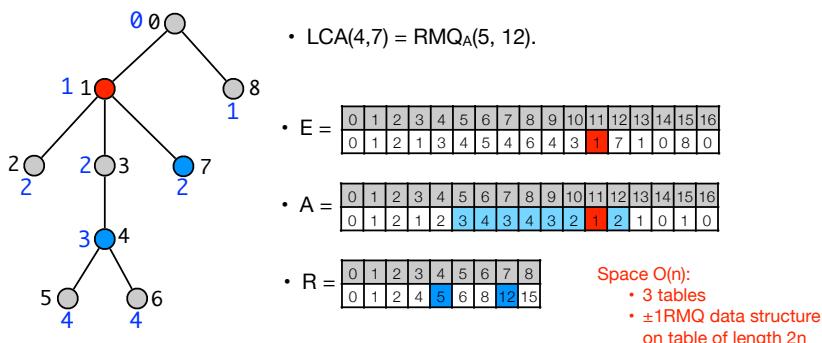
- **E: Euler tour representation:** preorder walk, write node preorder number of node when met.
- **A: depth of node node in $E[i]$.**
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- **LCA(i, j) = $E[\text{RMQ}_A(R[i], R[j])]$.**

LCA to ± 1 RMQ



- **E: Euler tour representation:** preorder walk, write node preorder number of node when met.
- **A: depth of node node in $E[i]$.**
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- **LCA(i, j) = $E[\text{RMQ}_A(R[i], R[j])]$.**

LCA to ± 1 RMQ



- **E: Euler tour representation:** preorder walk, write node preorder number of node when met.
- **A: depth of node node in $E[i]$.**
- **R: first occurrence in E of node with preorder number i**
- **LCA(i, j) = $E[\text{RMQ}_A(R[i], R[j])]$.**

RMQ and LCA

- **Theorem.** RMQ and LCA can be solved in $O(n)$ space and $O(1)$ query time.

Segment trees

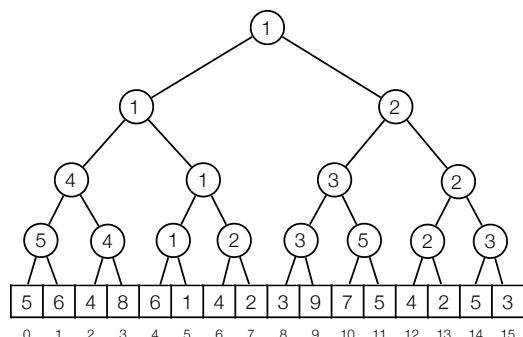
Dynamic Range Minimum Queries

Dynamic Range Minimum Queries

- Dynamic RMQ: Support following operations.
 - Add(i, k): Set $A[i] = A[i] + k$ (k can be negative).
 - RMQ(i, j)

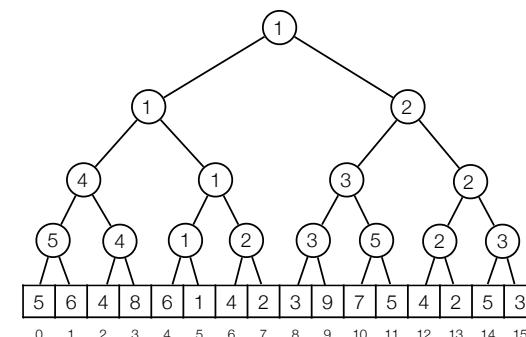
Segment trees

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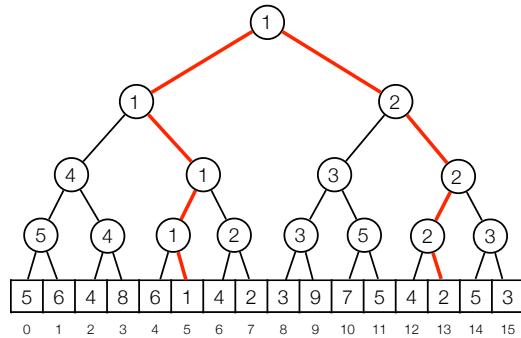
Segment trees

- Dynamic RMQ
 - RMQ(5,13) = ?



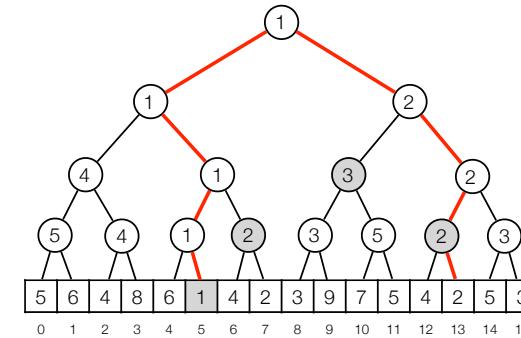
Segment trees

- Dynamic RMQ
 - $\text{RMQ}(5,13) = ?$



Segment trees

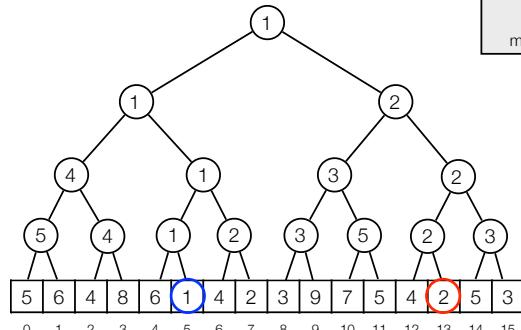
- Dynamic RMQ
 - $\text{RMQ}(5,13) = \text{Every interval can be composed of at most } 2 \log n \text{ intervals.}$



Segment trees

- Dynamic RMQ
 - $\text{RMQ}(5,13) = \text{INF}$

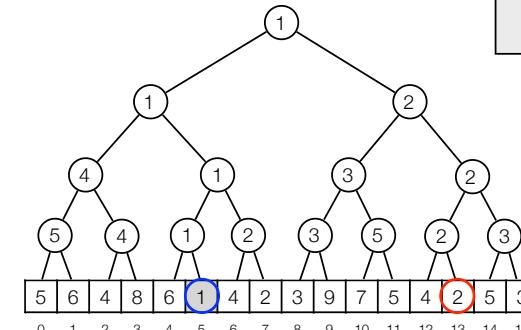
```
s = INF
while (a not right of b):
  if (a right child):
    s = min(s, tree[a])
    move a to the right
  if (b left child):
    s = min(s, tree[b])
    move b to the left
  move a and b to parents
```



Segment trees

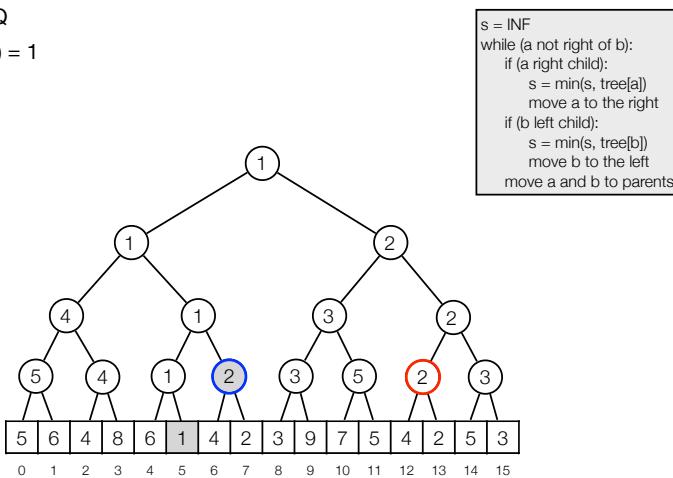
- Dynamic RMQ
 - $\text{RMQ}(5,13) = 1$

```
s = INF
while (a not right of b):
  if (a right child):
    s = min(s, tree[a])
    move a to the right
  if (b left child):
    s = min(s, tree[b])
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  move a and b to parents
```



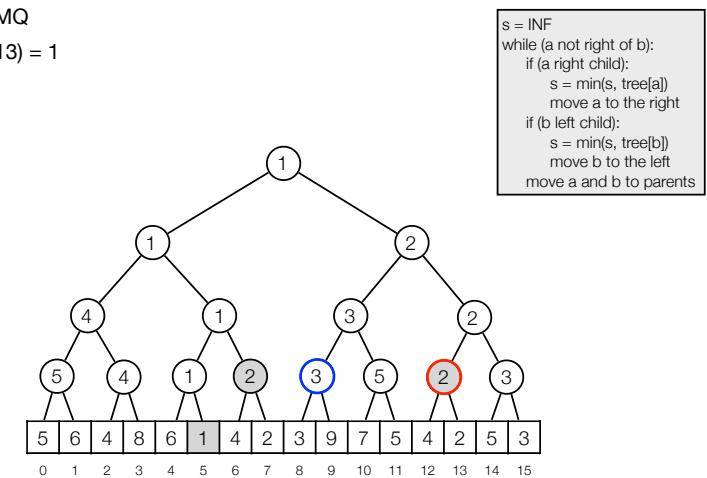
Segment trees

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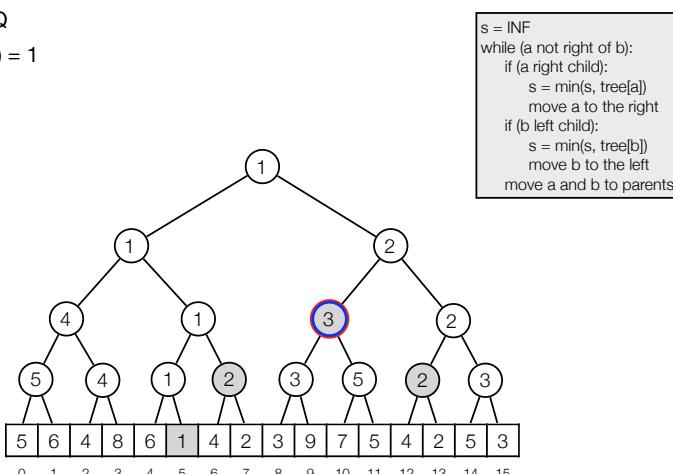
Segment trees

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Segment trees

- Dynamic RMQ
 - $\text{RMQ}(5,13) = 1$

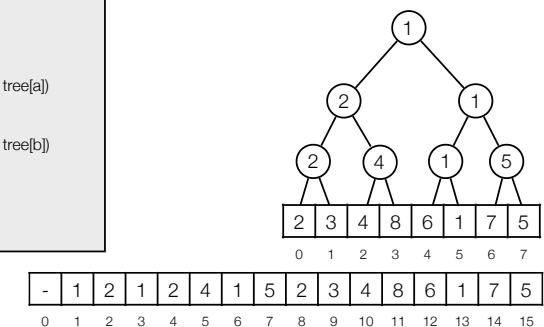


Implementation

- Implement tree using heap layout in array of length $2n$:
 - Root at position 1.
 - Children of node i at position $2i$ and $2i+1$.

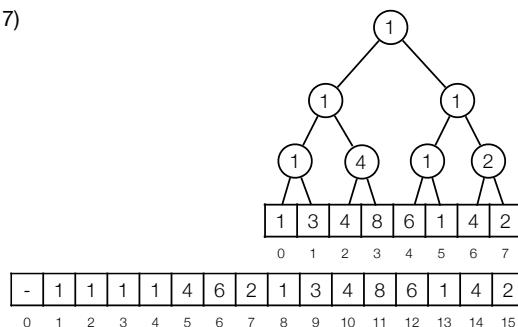
```

m = INFINITY
a += n, b += n
while (a ≤ b):
  if (a % 2 == 1):
    m = min(m, tree[a])
    a += 1
  if (b % 2 == 0):
    m = min(m, tree[b])
    b -= 1
  a = ⌊a / 2⌋
  b = ⌊b / 2⌋
return m
  
```



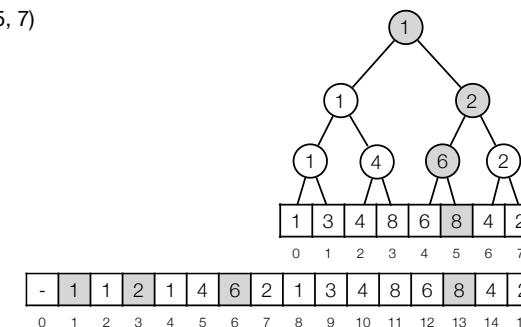
Updates

- Add(5, 7)



Updates

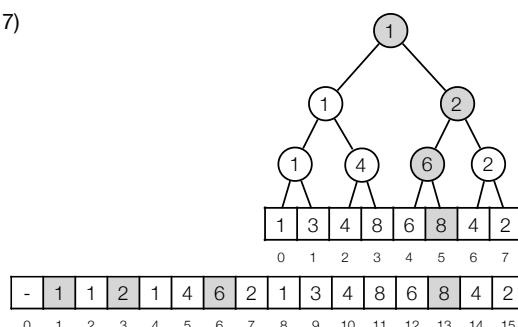
- Add(5, 7)



```
Add(i, k):
    i += n
    tree[i] += k
    i = ⌊i / 2⌋
    while (i ≥ 1):
        tree[x] = min(tree[2*i], tree[2*i + 1])
        i = ⌊i / 2⌋
```

Updates

- Add(5, 7)



```
Add(i, k):
    i += n
    tree[i] += k
    i = ⌊i / 2⌋
    while (i ≥ 1):
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        i = ⌊i / 2⌋
```

Segment trees

- Space: O(n)
- Time:
 - O(n) for preprocessing.
 - O(log n) for both add and RMQ.